

Green's Theorem

$$F(x,y) = (p(x,y), q(x,y)) \quad \left(\begin{array}{l} \text{assume} \\ \text{smooth functions} \end{array} \right)$$

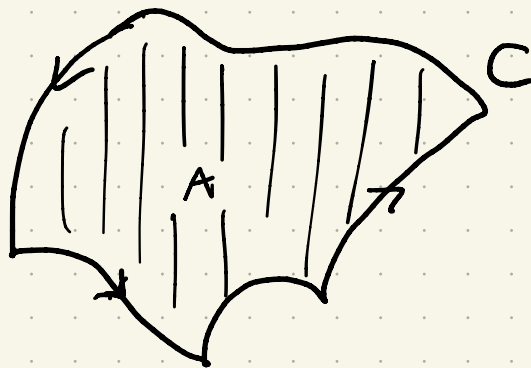
$$\int_C F = \int_a^b F(c(t)) \cdot c'(t) dt = \int_C p(x,y) dx + q(x,y) dy$$

$$\text{abbr. as } \int_C F = \int_C p dx + q dy$$

$$\begin{aligned} \text{reasonable notation since } F(c(t)) \cdot c'(t) dt \\ = p \frac{dx}{dt} + q \frac{dy}{dt} \end{aligned}$$

Thm 1.1. (Green's Theorem) Let (p, q) be a vector field on A . Let A be the interior of a closed path C oriented CCW. Then

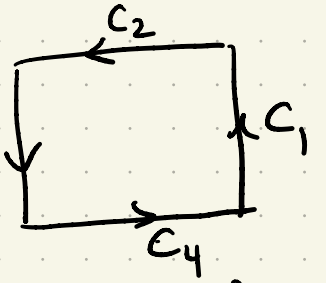
$$\int_C p dx + q dy = \iint_A \left(\frac{\partial q}{\partial x} - \frac{\partial p}{\partial y} \right) dy dx.$$



Proving it in full generality is difficult, but we can show it for certain types of regions.

Suppose A is a rectangular region $[a, b] \times [c, d]$.

$$\begin{aligned} \textcircled{1} \quad \iint_A \frac{\partial p}{\partial y} dy dx &= \int_a^b \int_c^d \frac{\partial p(x, y)}{\partial y} dy dx \\ &= \int_a^b p(x, y) \Big|_{y=c}^{y=d} dx = \int_a^b (p(x, d) - p(x, c)) dx \\ &= - \int_{c_2} p dx - \int_{c_4} p dx \end{aligned}$$



$$C = (c_1, c_2, c_3, c_4)$$

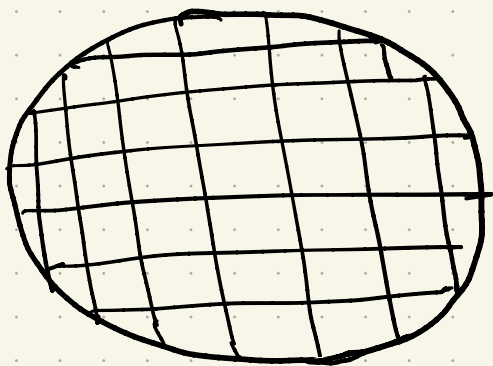
on vertical segments, $dx = 0 \Rightarrow \int_{c_1} p dx = 0$

$$\text{so } \iint_A \frac{\partial p}{\partial y} dy dx = \int_C p dx \quad \int_{c_3} p dx = 0$$

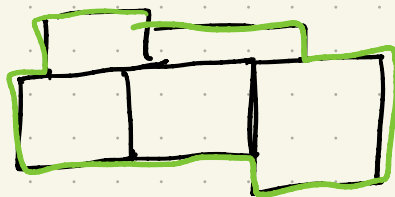
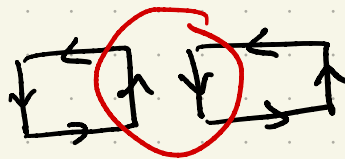
$$\begin{aligned} \textcircled{2} \quad \iint_A \frac{\partial q}{\partial x} dx dy &= \int_c^d \int_a^b \frac{\partial q}{\partial x} dx dy = \int_c^d [q(b, y) - q(a, y)] dy \\ &= \int_{c_1} q dy + \int_{c_3} q dy = \int_C q dy \end{aligned}$$

$$\textcircled{1} + \textcircled{2} \Rightarrow \iint_A \left(\frac{\partial q}{\partial x} - \frac{\partial p}{\partial y} \right) dy dx = \int_C p dx + q dy \quad \square$$

We can then approximate regions by rectangles.



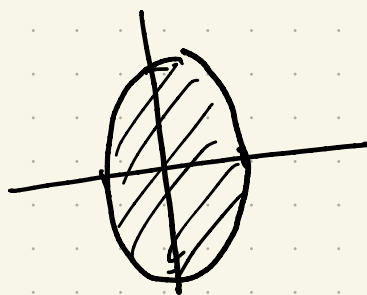
notice that on two adjacent rectangles, cancellations occur, and you're left with the boundary.



Ex 1: $F(x, y) = (y + 3x, 2y - x)$

$C: 4x^2 + y^2 = 4$

$\frac{\partial p}{\partial y} = 1, \frac{\partial q}{\partial x} = -1$

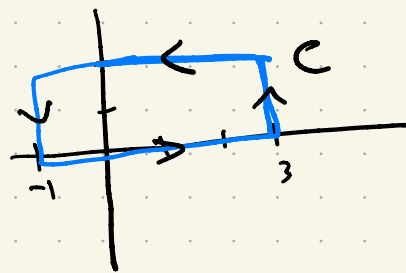


$$\int_C p dx + q dy = \iint_A -2 dy dx = -2 \cdot \text{Area}(A)$$

$$= -2 \cdot \pi \cdot 1 \cdot 2 = -4\pi.$$

Ex 2: $F = (3xy, x^2)$

$$\int p dx + q dy$$



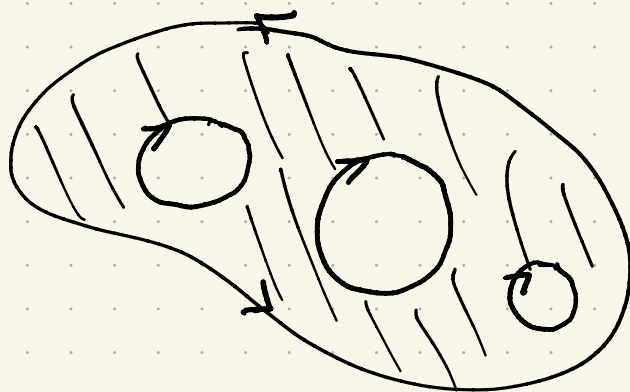
$$\begin{aligned} \int_C p dx + q dy &= \iint_R \left(\frac{\partial q}{\partial x} - \frac{\partial p}{\partial y} \right) dy dx \\ &= \int_{-1}^3 \int_0^2 (2x - 3x) dy dx = \int_{-1}^3 \int_0^2 -x dy dx \\ &= \int_{-1}^3 -2x dx = -x^2 \Big|_{-1}^3 = -9 + 1 = -8. \end{aligned}$$

This is much better than parametrizing the boundary.

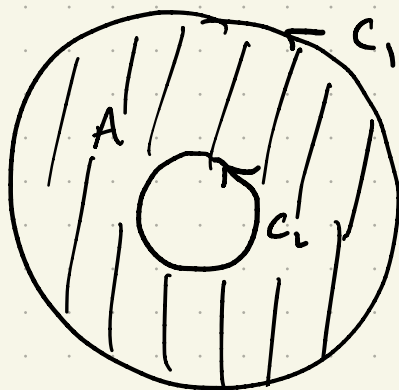
Green's Theorem, general version: Let A be a region in the plane whose boundary consists of a finite # of curves, each one oriented s.t. A lies to the left.

Then

$$\int_C p dx + q dy = \iint_A \left(\frac{\partial q}{\partial x} - \frac{\partial p}{\partial y} \right) dy dx$$



Ex: Let A be the region between two concentric circles with CCW orientation.



Applying Green's theorem here would require us to reverse C_2 , so the integral in Green's formula would be

$$\int_{C_1} p dx + q dy + \int_{C_2^-} p dx + q dy = \iint_A \left(\frac{\partial q}{\partial x} - \frac{\partial p}{\partial y} \right) dx dy$$

$$\int_{C_1} p dx + q dy \stackrel{||}{=} \int_{C_2} p dx + q dy$$

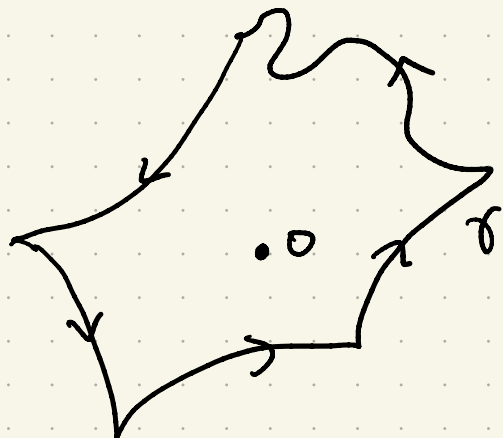
If $\frac{\partial p}{\partial y} = \frac{\partial q}{\partial x}$, then we have

$$\int_{C_1} p dx + q dy = \int_{C_2} p dx + q dy.$$

If F is conservative, we always have $D_2 p = D_1 q$.

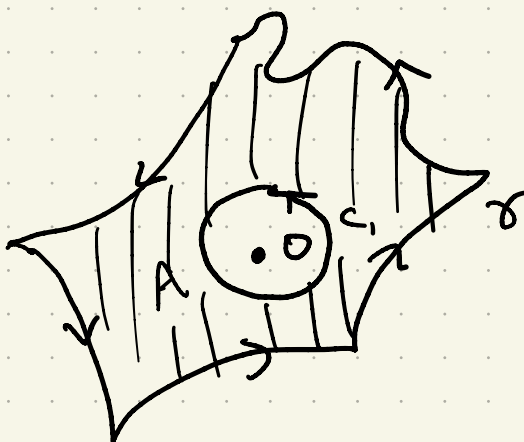
But we can have $D_2 p = D_1 q$ for a nonconservative vector field.

Ex: $G = \left(\frac{-y}{x^2+y^2}, \frac{x}{x^2+y^2} \right)$



$$\int_{\sigma} G = ?$$

Note: Green's Theorem doesn't immediately apply since the interior of C contains a pt. for which G is undefined.



Introduce C_1 , a circle centered at O .

$$\text{Then } \int_{\sigma} G = \int_{C_1} G$$

$\underbrace{\hspace{2cm}}$
 we know
 this guy.
 $= 2\pi$

Note: IF σ does not enclose the origin, then

$$\int_{\sigma} G = 0. \text{ Why?}$$

2) Divergence and Rotation

$F = (p, q)$ vector field $p, q: U \subseteq \mathbb{R}^2 \rightarrow \mathbb{R}$

The divergence of F is

$$\operatorname{div} F = D_1 p + D_2 q = \frac{\partial p}{\partial x} + \frac{\partial q}{\partial y}$$

The rotation of F is

$$\operatorname{rot} F = D_1 q - D_2 p = \frac{\partial q}{\partial x} - \frac{\partial p}{\partial y}$$

Note that $\operatorname{rot} F$ is exactly the quantity appearing in Green's theorem.

It may help in the following discussion to imagine that F is describing a fluid flow in a region.

Green's Theorem states

$$\iint_A \operatorname{rot} F \, dy dx = \int_a^b F(c(t)) \cdot c'(t) \, dt$$

where A is the region inside C oriented CCW.

Now, $\|C'(t)\| = \frac{ds}{dt}$, the speed.

Here $s(t)$ is the distance traveled.

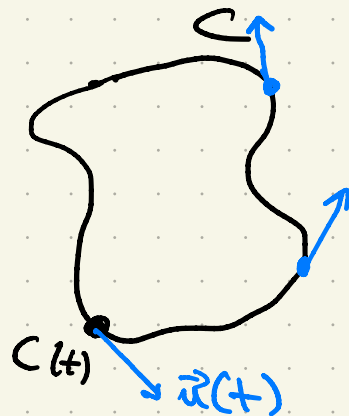
Let \vec{u} be a unit vector in the tangential direction of C at time t .

$$C'(t) = \vec{u}(t) \frac{ds}{dt}$$

Then

$$\iint_A \text{rot } F \, dy \, dx = \int_C F \cdot \vec{u} \, ds$$

C \hookrightarrow the more aligned F is with the velocity, the more this integral is picking up.



Thm 2.1 Let D_r be the disk of radius r at a point P . Let C_r be the boundary of D_r .

Let F be a vector field defined on the closed disk. Let $A(r) = \pi r^2$.



Then

$$(\text{rot } F)(P) = \lim_{r \rightarrow 0} \frac{1}{A(r)} \int_{C_r} F \cdot \vec{u}$$

Proof: Fix $x = (x, y)$ in the disk.

$$\operatorname{rot} F(x) = \operatorname{rot} F(P) + h(x)$$

where $\lim_{x \rightarrow P} h(x) = 0$ (this can be done by continuity).

$$\frac{1}{A(r)} \int_{C_r} F \cdot \vec{u} ds = \frac{1}{A(r)} \iint_{D_r} \operatorname{rot} F dy dx$$

$$= \frac{1}{A(r)} \iint_{D_r} \underbrace{\operatorname{rot} F(P)}_{\text{constant}} dy dx + \frac{1}{A(r)} \iint_{D_r} h(x, y) dy dx$$

$$= \operatorname{rot} F(P) + \frac{1}{A(r)} \iint_{D_r} h(x, y) dy dx$$

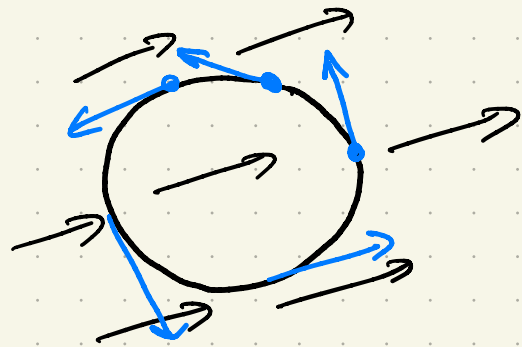
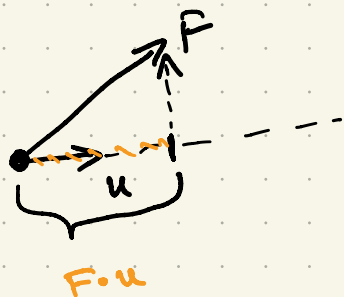
$$\left| \frac{1}{A(r)} \iint_{D_r} h(x, y) dy dx \right| \leq \frac{1}{A(r)} \iint_{D_r} |h(x, y)| dy dx$$

$$\leq \frac{1}{A(r)} \iint_{D_r} \max_{D_r} |h(x, y)| dy dx$$

$$= \max_{D_r} |h(x, y)| \frac{1}{A(r)} \iint_{D_r} dy dx = \max_{D_r} |h(x, y)|$$

↓
0
as $r \rightarrow 0$. \square

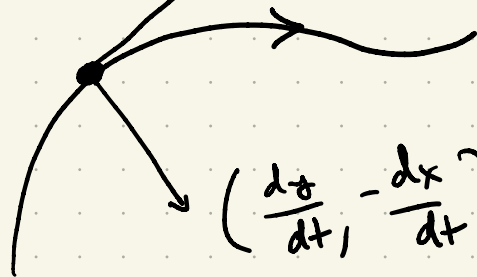
$F \cdot \vec{u}$ is the component of F in the tangential direction.



Thus $\text{rot} F(P)$ gives a quantitative measure of how much the vector field circulates around a given point.

$$c(t) = (x(t), y(t)) \quad a \leq t \leq b$$

$$\left(\frac{dx}{dt}, \frac{dy}{dt} \right) = c'(t)$$

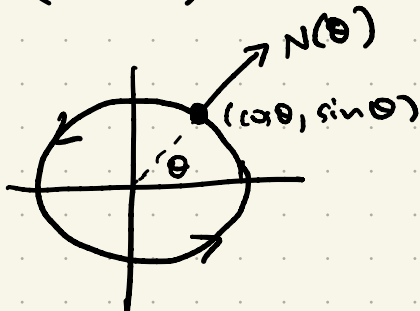


$$\left(\frac{dy}{dt}, -\frac{dx}{dt} \right) = N$$

right normal vector

Ex: $c(\theta) = (\cos \theta, \sin \theta)$

$$N(\theta) = (\cos \theta, \sin \theta)$$



The position vector for a parametrized circle is always normal to the circle itself.

We can now look at $F(c(t)) \cdot N(t)$
rather than $F(c(t)) \cdot c'(t)$

Thm: A = region, interior of a closed CCW
curve C . F vector field on A . Then

$$\iint_A (\operatorname{div} F) dy dx = \int_C F(c(t)) \cdot N(t) dt$$

Pf: your HW.

$$c'(t) = \left(\frac{dx}{dt}, \frac{dy}{dt} \right), \text{ so}$$

$$\|N(t)\| = \|c'(t)\| = v(t) \xrightarrow{\text{speed}}$$

$$\text{dist traveled } s(t) = \int v(t) dt, \text{ so } \frac{ds}{dt} = v(t)$$

$$\vec{n}(t) = \frac{N(t)}{\|N(t)\|}$$

$$N(t) = \|N(t)\| \vec{n}(t) = \frac{ds}{dt} \vec{n}(t)$$

$$\text{so } \iint_A \operatorname{div} F dy dx = \int_C F \cdot \vec{n} ds$$

Thm: $(\operatorname{div} F)(P) = \lim_{r \rightarrow 0} \frac{1}{A(r)} \int_{C_r} F \cdot \vec{n} \, ds$

Pf: Similar

$F \cdot \vec{n}$ is the component of f normal to the curve. Thus the integral on the right side above is measuring some kind of outward/inward flow.